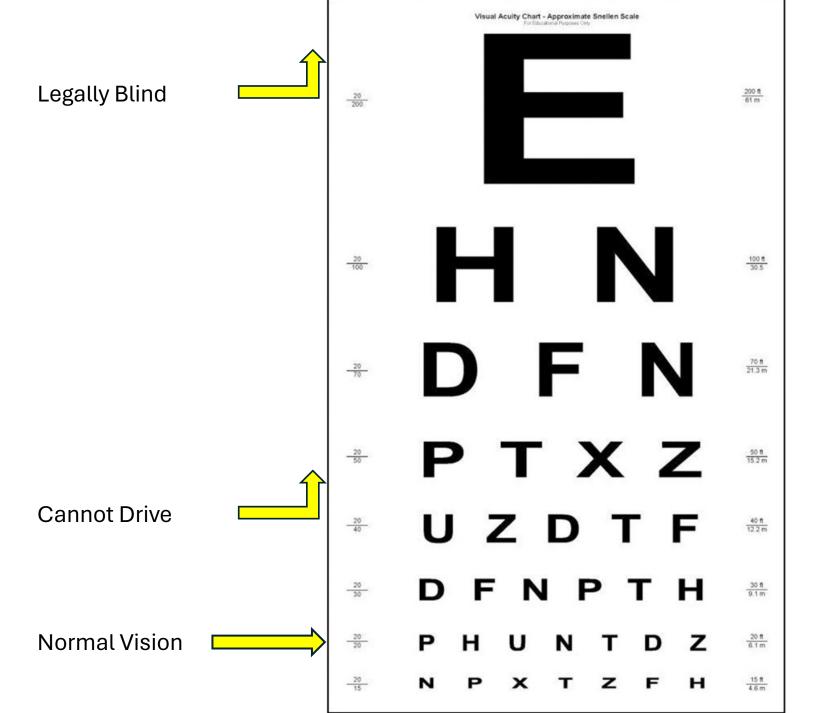
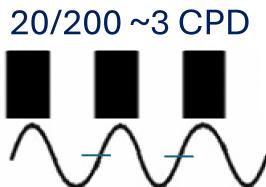


Designing Visually Accessibility Spaces original mission:

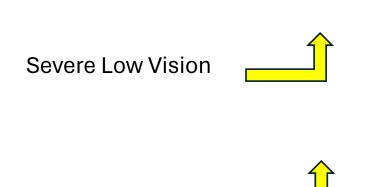
To enable the designer to analyze and improve the visibility of hazards to aid in the creation of architectural spaces that are accessible to those with vision impairment, who make use of vision for mobility.

Today I will share how these tools can aid in optimizing face recognition and a few other unexpected applications.

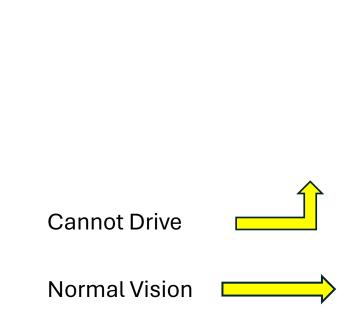


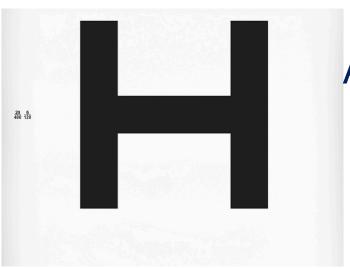


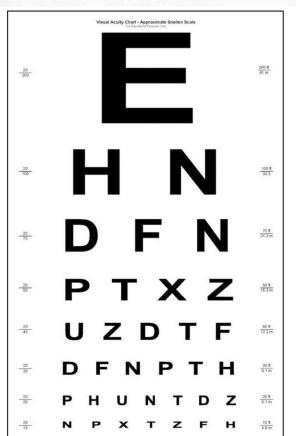




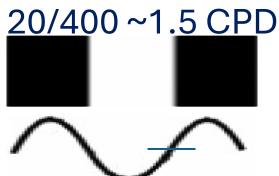
Legally Blind





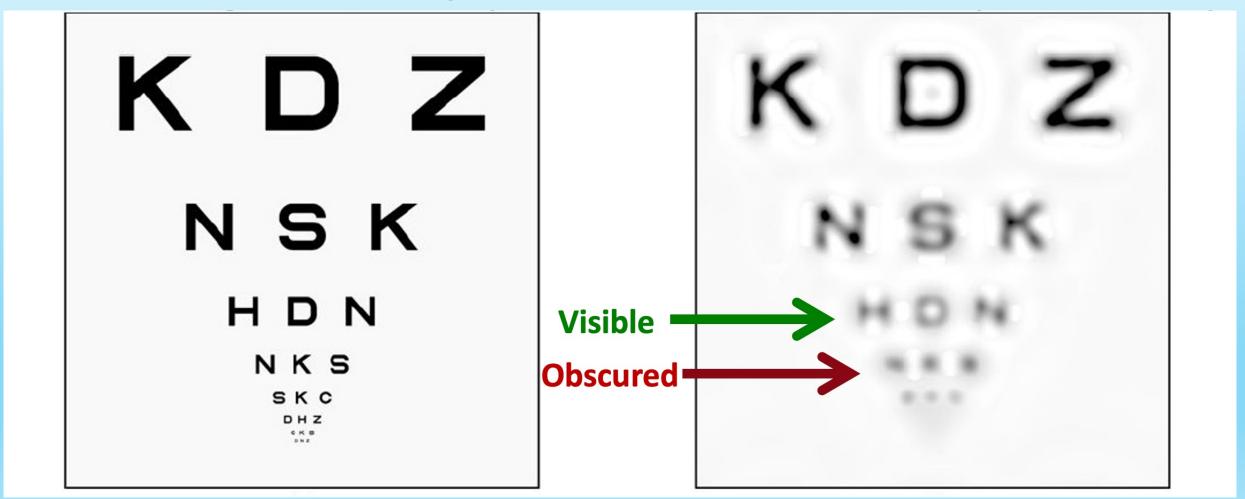


Acuity Used In Studies



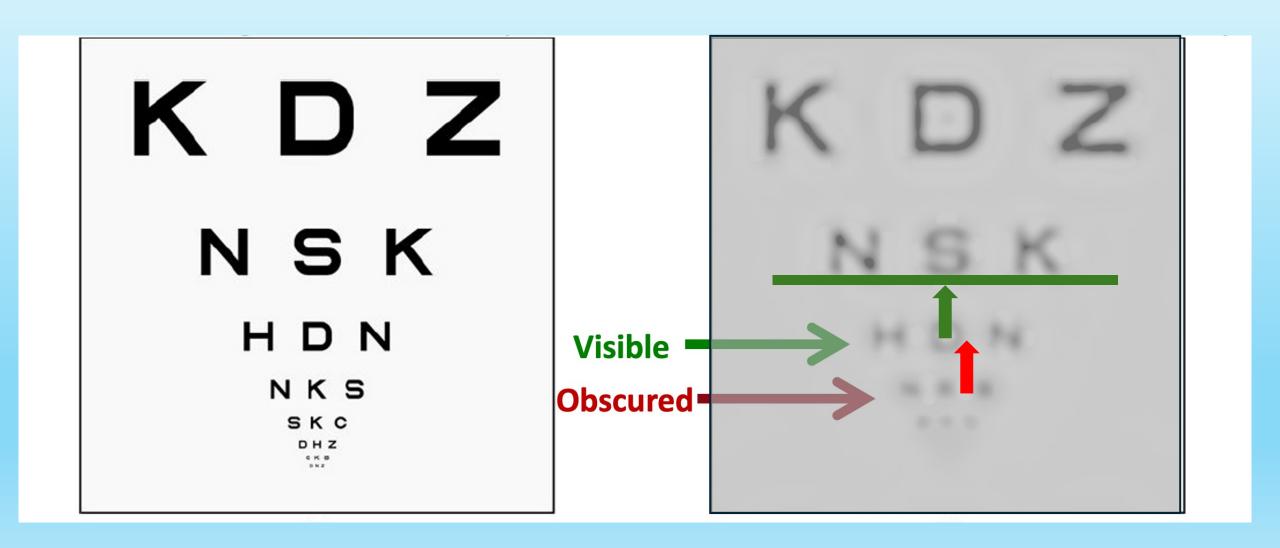
At a specified acuity,

DeVAS removes image details predicted NOT to be visible, while leaving intact, details predicted to be visible

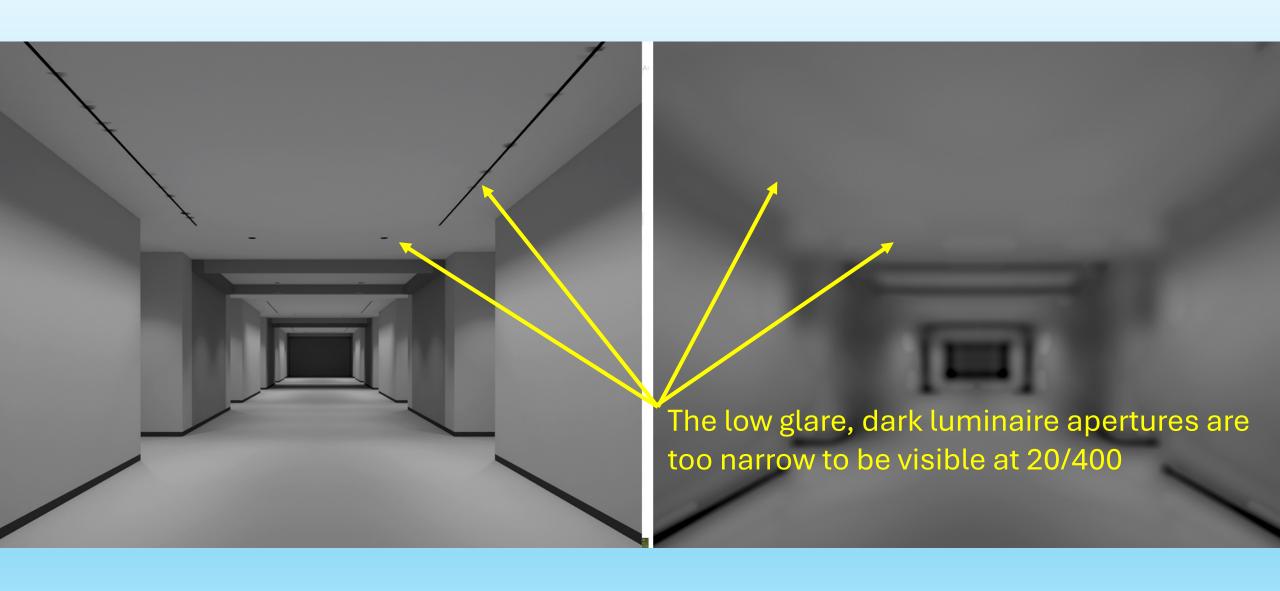


DeVAS processed at a specific acuity

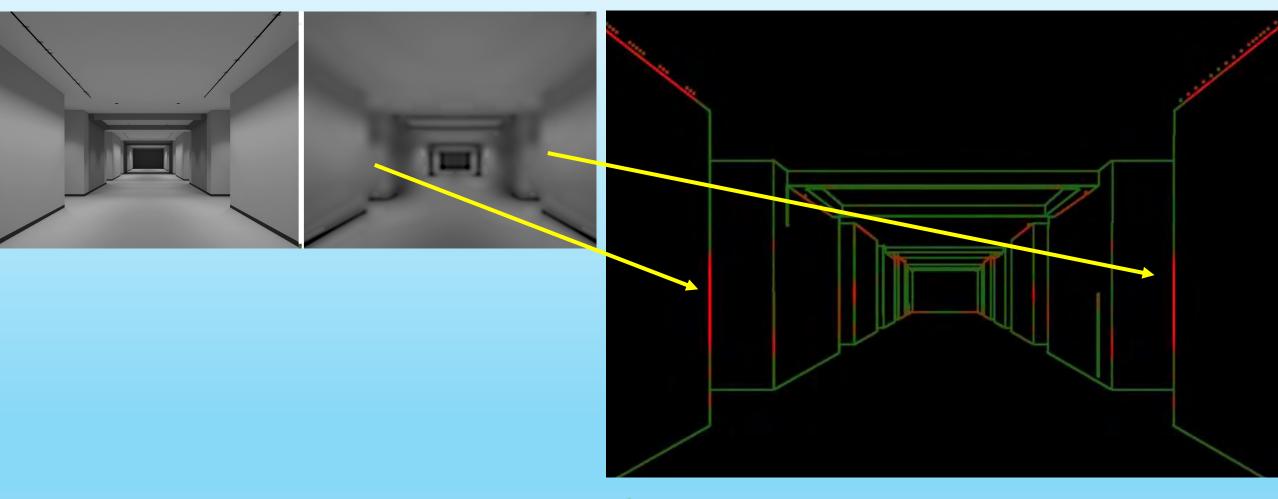
DeVAS removes image details predicted to be not visible As Contrast Decreases, Acuity Lowers... details are harder to see



DeVAS removes image details predicted to be not visible

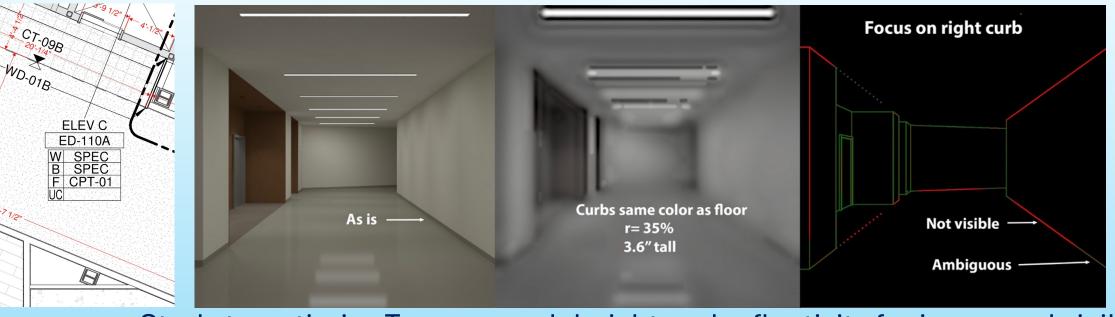


DeVAS can objectively determine the Visibility of Edges for a specified acuity

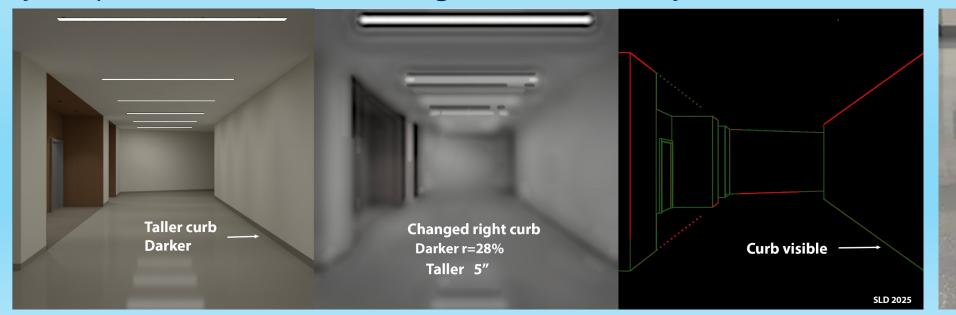


Green edges predicted visible Red edges predicted not visible

DeVAS can be used iteratively to optimize the visibility of edges



Study to optimize Terrazzo curb height and reflectivity for increased visibility











Face Recognition: observations from low some vision articles, 1992 through 2024:

The inability to recognize known individuals, setting aside audio or haptic cues, severely limits the visually impaired in their social interactions, which can lead to social disengagement, and can put them at risk from a security perspective.















Face Recognition: observations from low some vision articles, 1992 through 2024:

Reduced contrast sensitivity in low vision may be an important factor in limiting performance in everyday tasks such as face recognition. Face recognition is illumination-dependent, indicating that face-recognition processes are sensitive to either the direction of lighting or the resultant pattern of shading. *This can be enhanced by compensating for the viewer's reduced contrast sensitivity...* increasing the contrast of the face with lighting, while avoiding shadows that mask or distort features.









Face Recognition: observations from low some vision articles, 1992 through 2024:

Reduced contrast sensitivity in low vision may be an important factor in limiting performance in everyday tasks such as face recognition. Face recognition is illumination-dependent, indicating that face-recognition processes are sensitive to either the direction of lighting or the resultant pattern of shading. *This can be enhanced by compensating for the viewer's reduced contrast sensitivity...* increasing the contrast of the face with lighting, while avoiding shadows that mask or distort features.





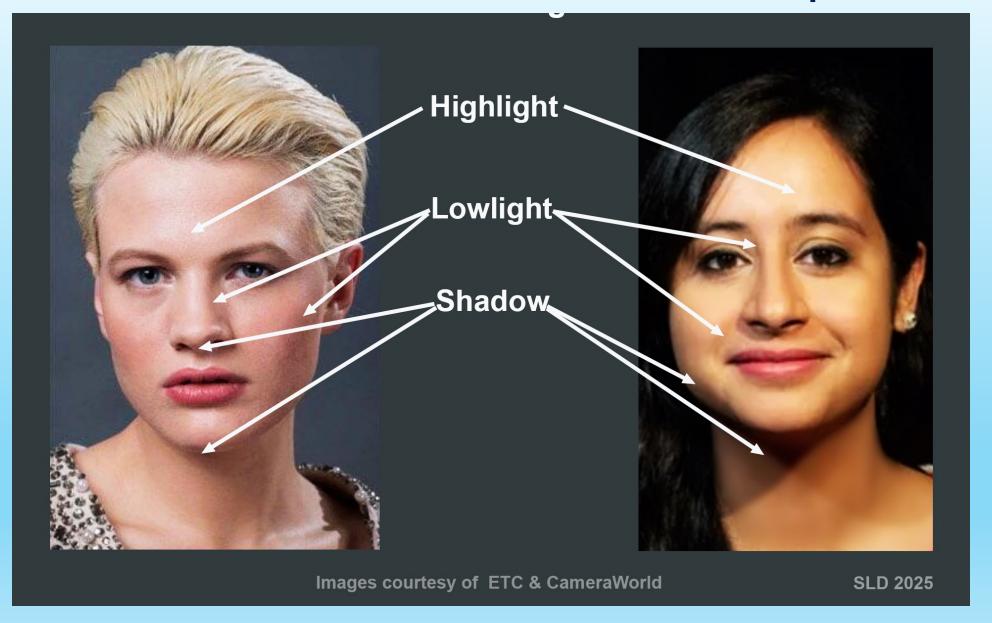




Face Recognition: observations from low some vision articles, 1992 through 2024:

Reduced contrast sensitivity in low vision may be an important factor in limiting performance in everyday tasks such as face recognition. Face recognition is illumination-dependent, indicating that face-recognition processes are sensitive to either the direction of lighting or the resultant pattern of shading. This can be enhanced by compensating for the viewer's reduced contrast sensitivity... increasing the contrast of the face with lighting, while avoiding shadows that mask or distort features.

Face Visibility is optimized with illumination from multiple overlapping directions and contrast to reveal facial contours and expressions

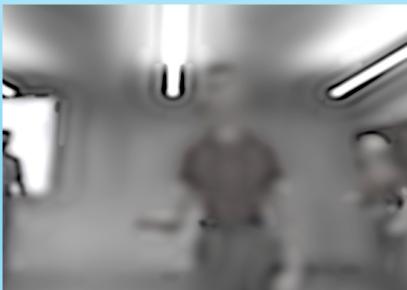


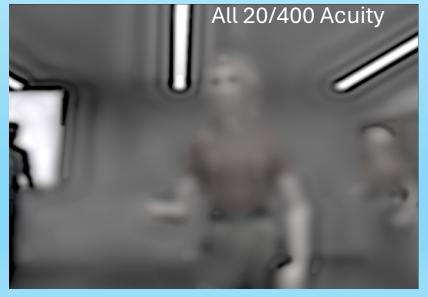
DeVAS can be used to subjectively explore the visibility of faces...









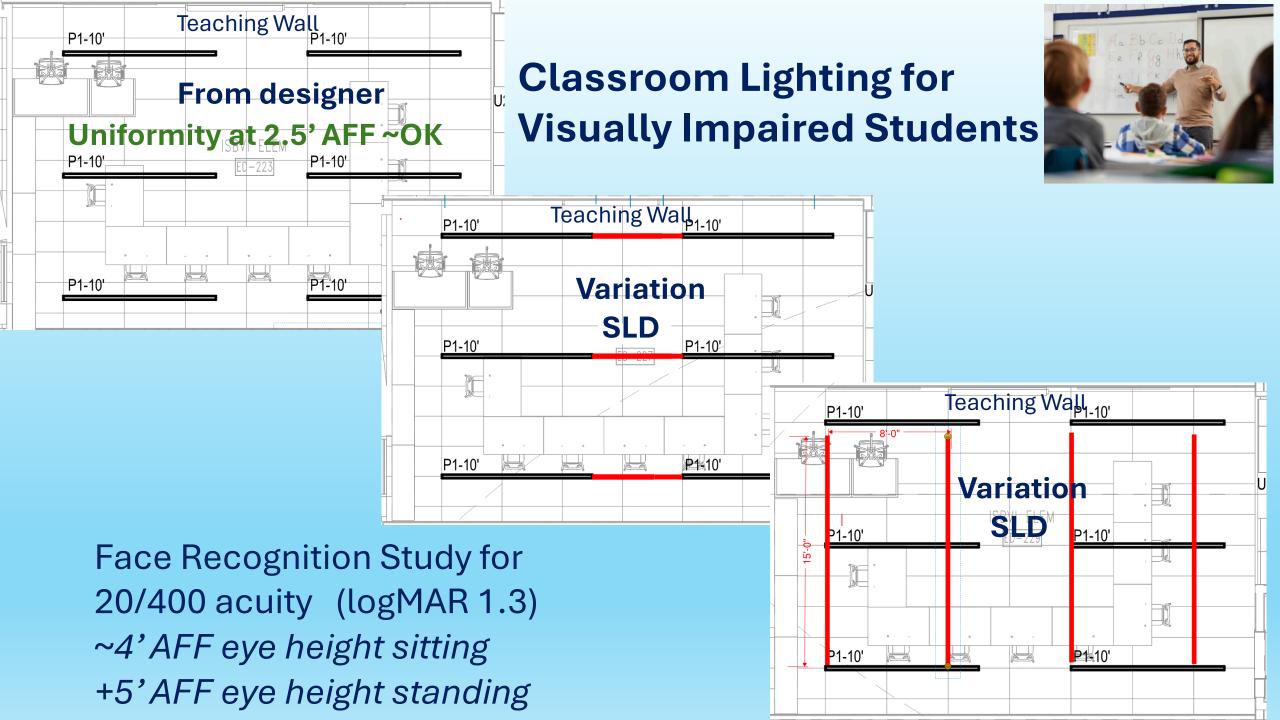


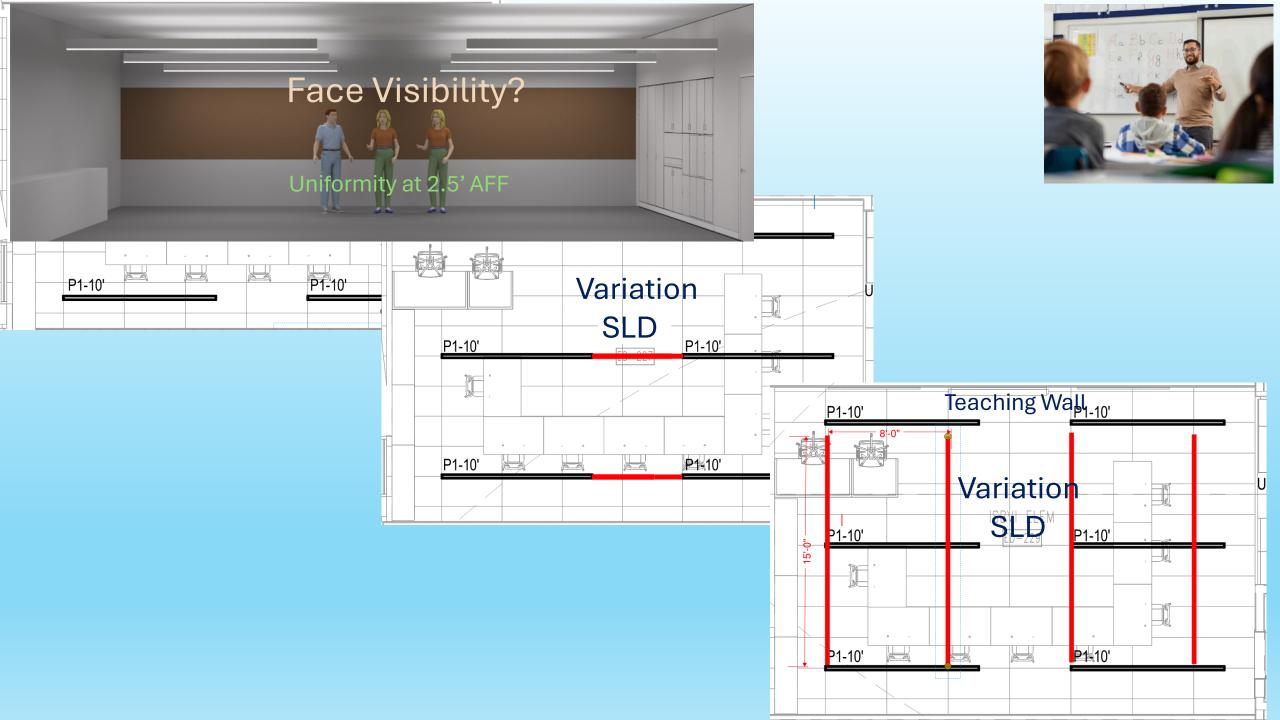


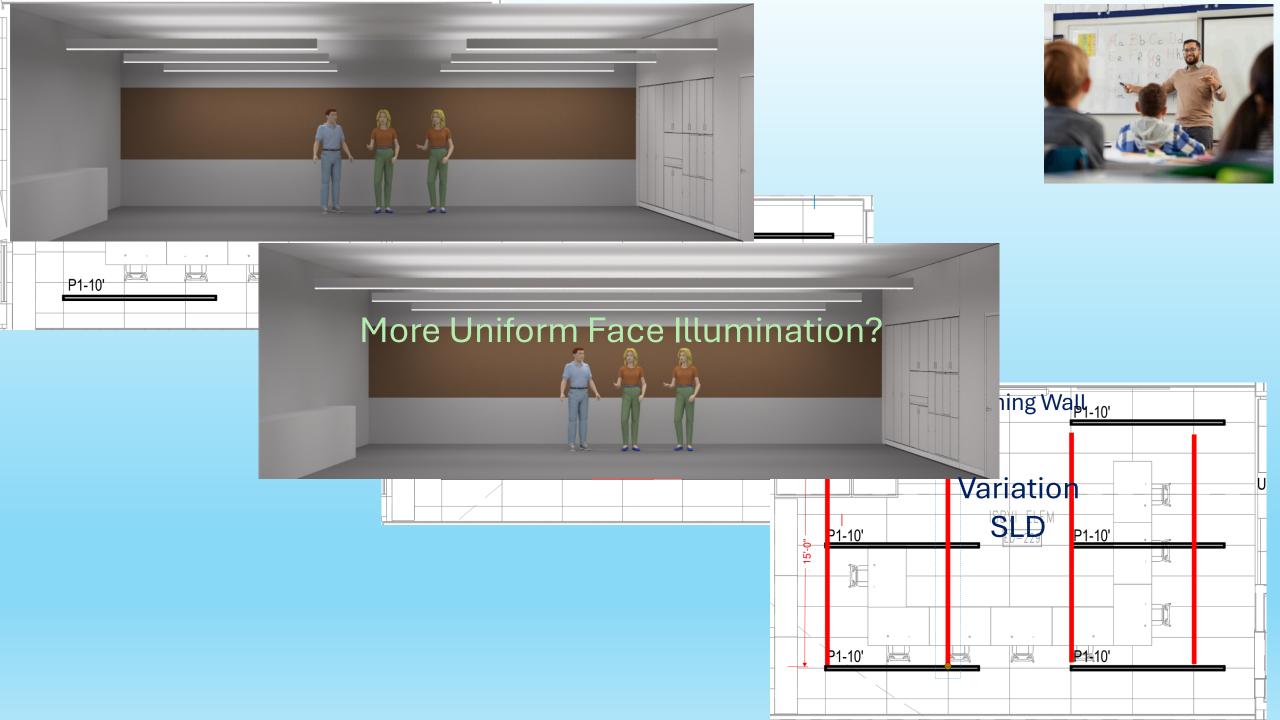
Dir-Ind with No DL

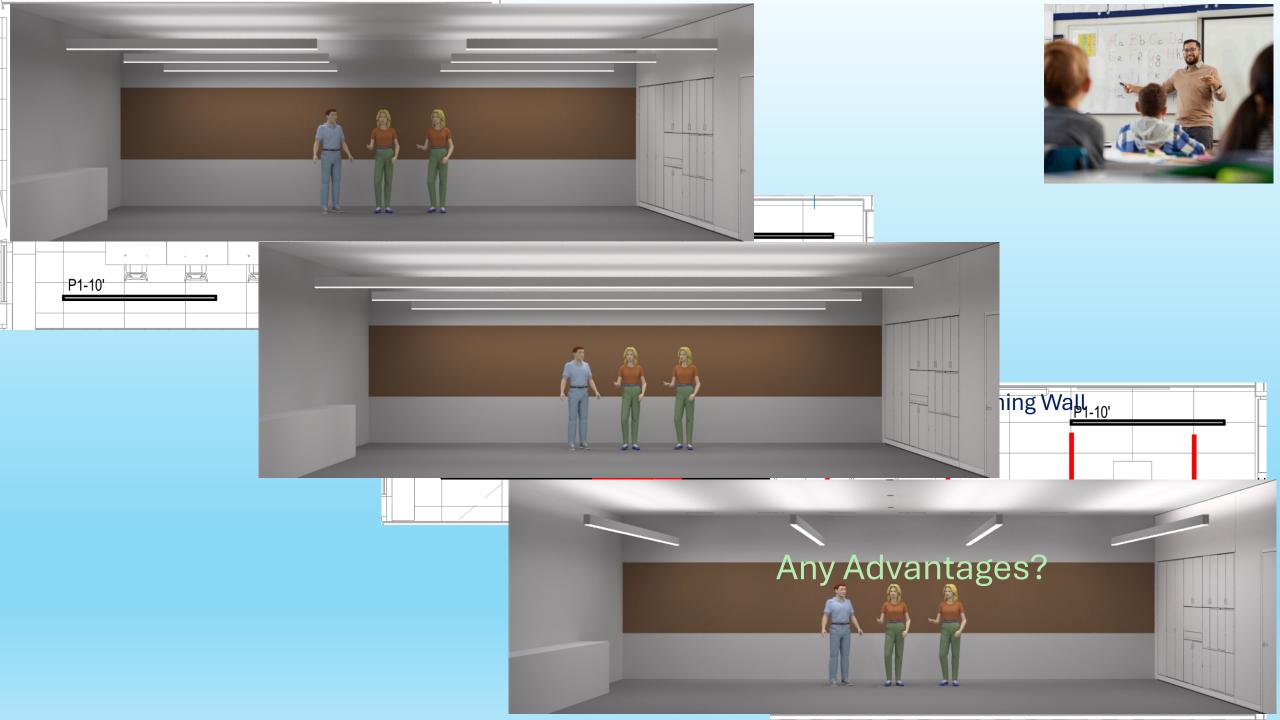
Dir with DL

Ind with DL











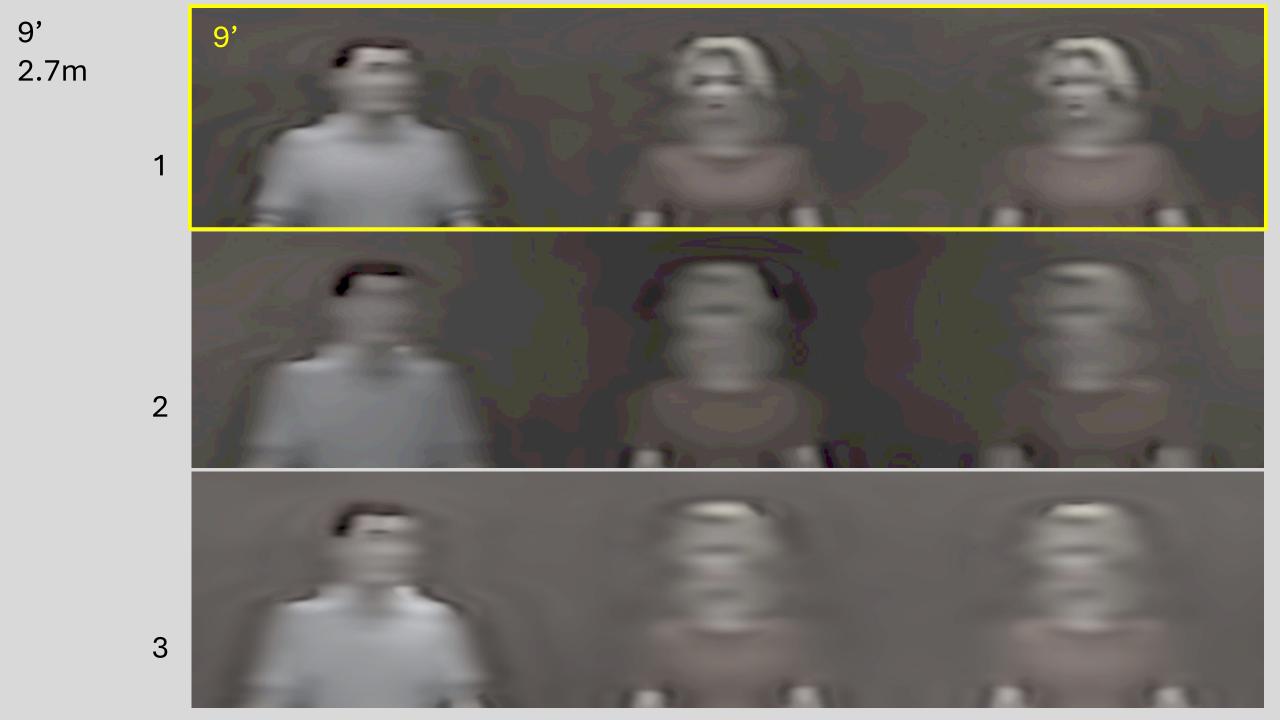




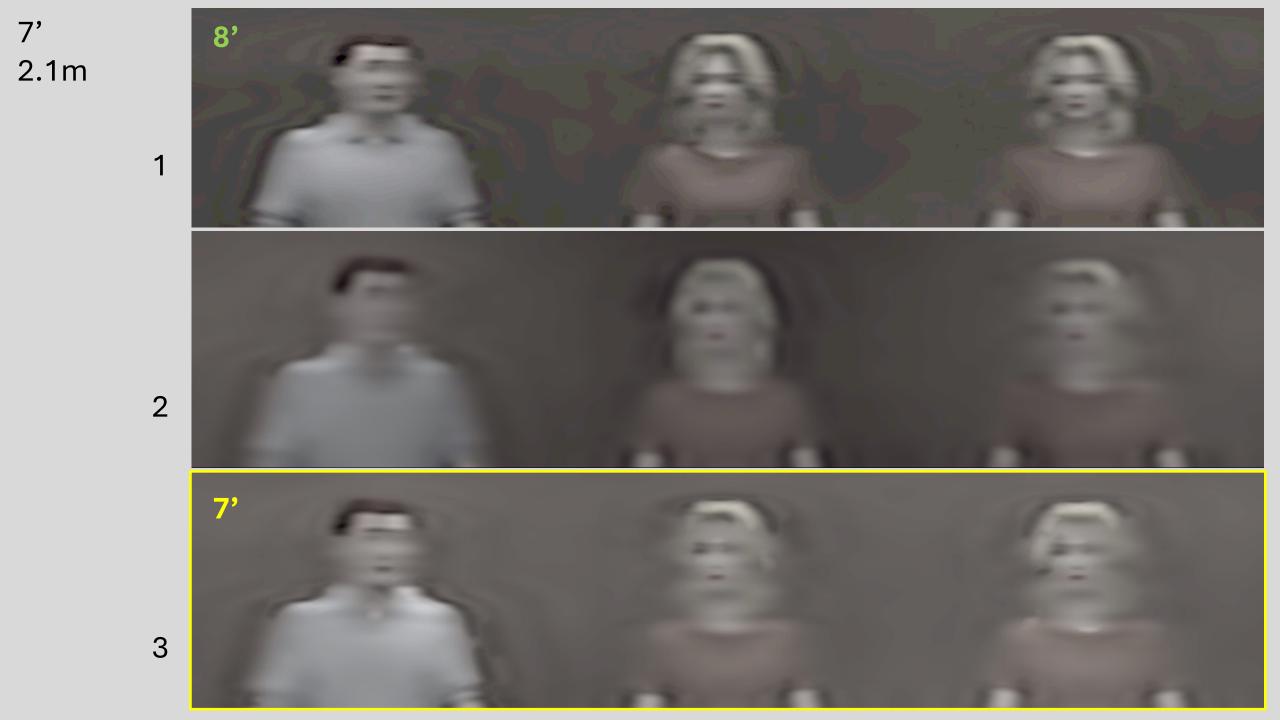




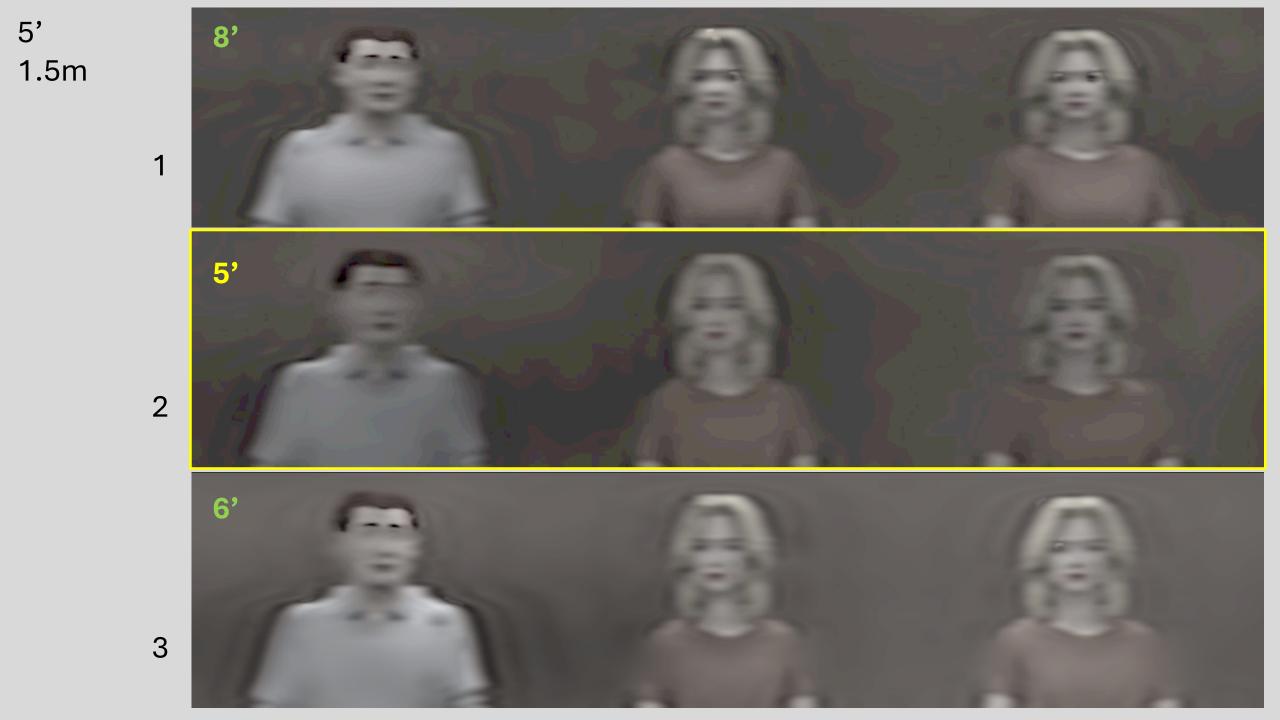


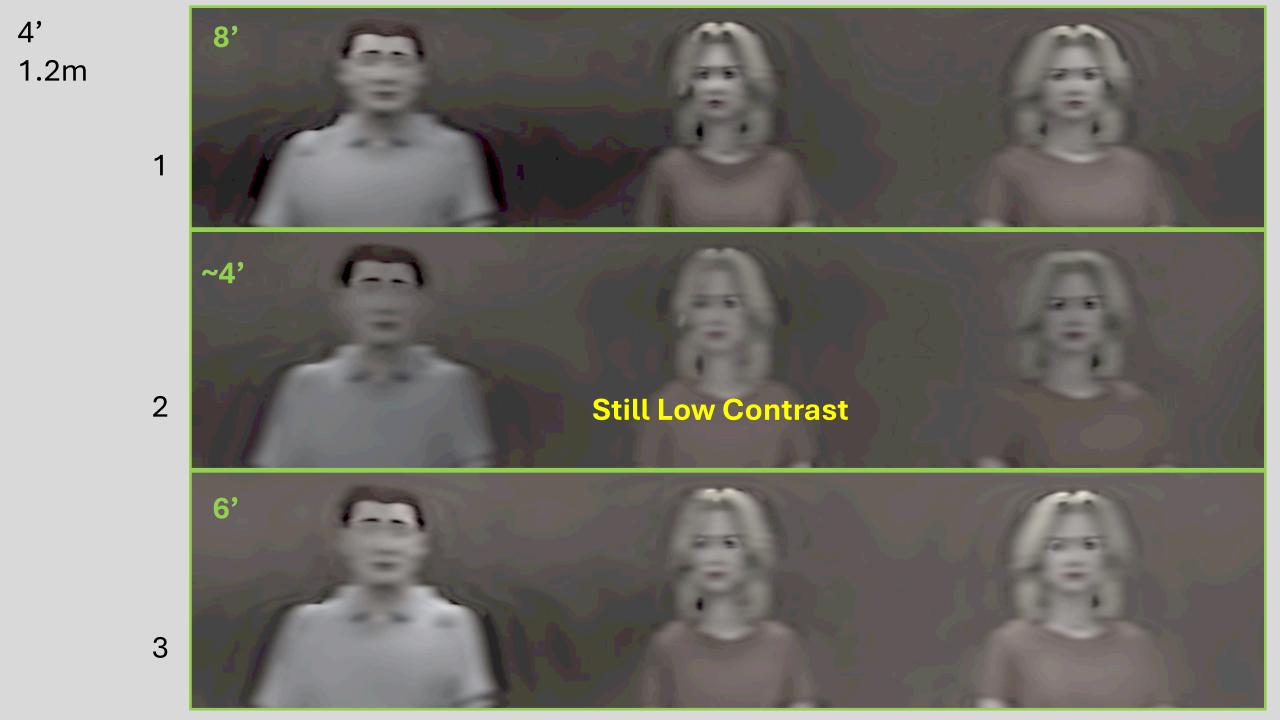


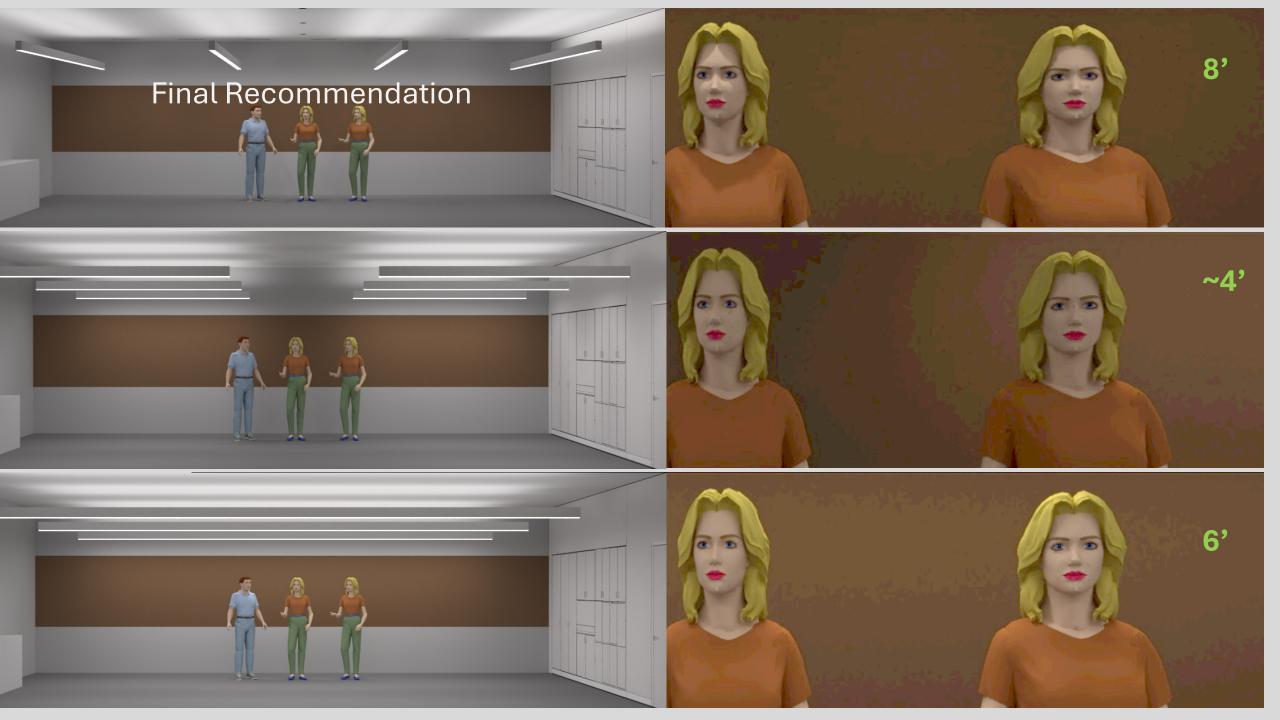


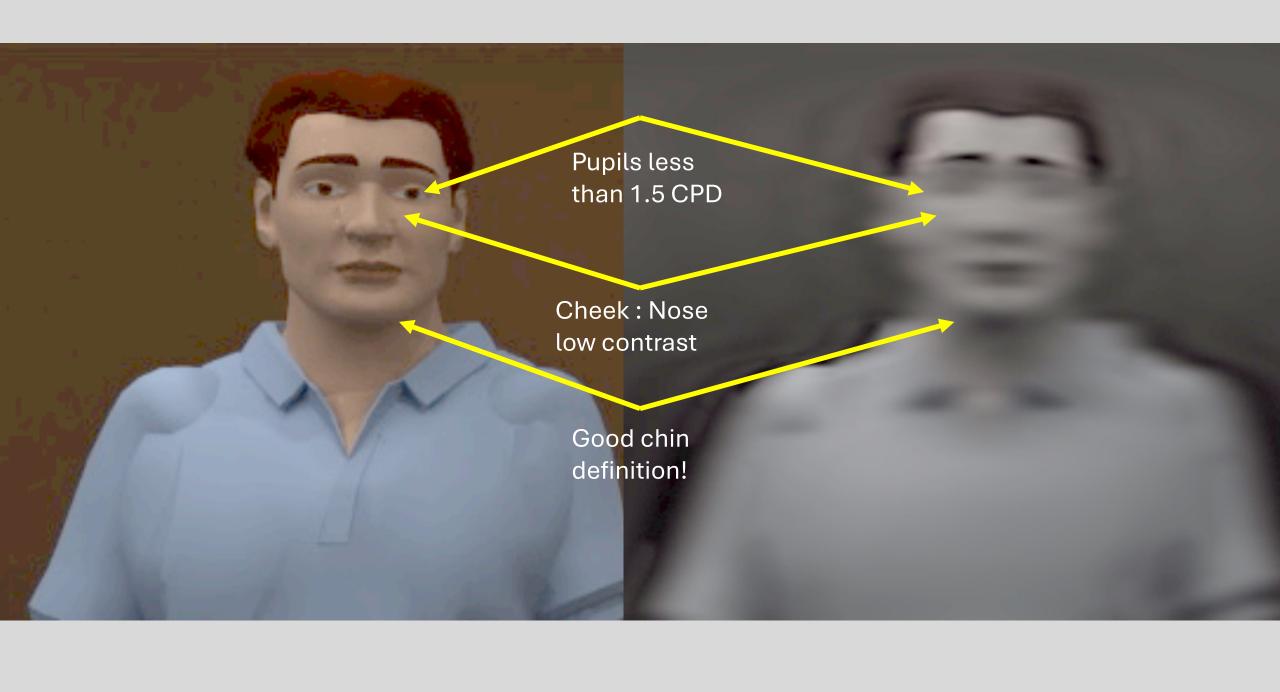


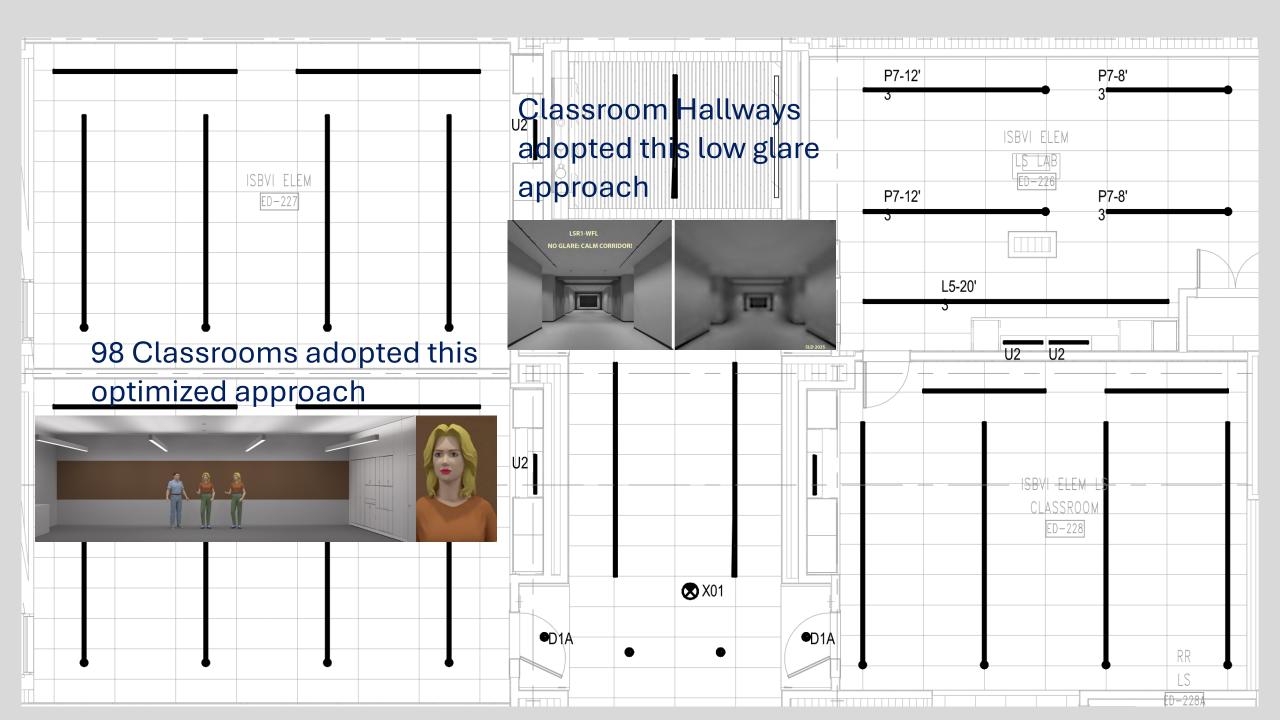








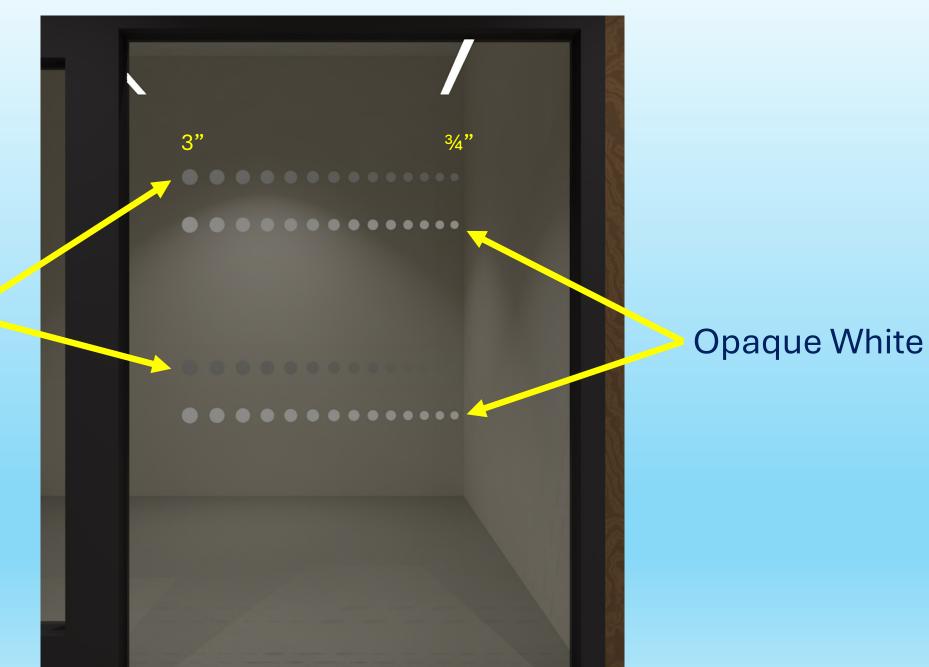




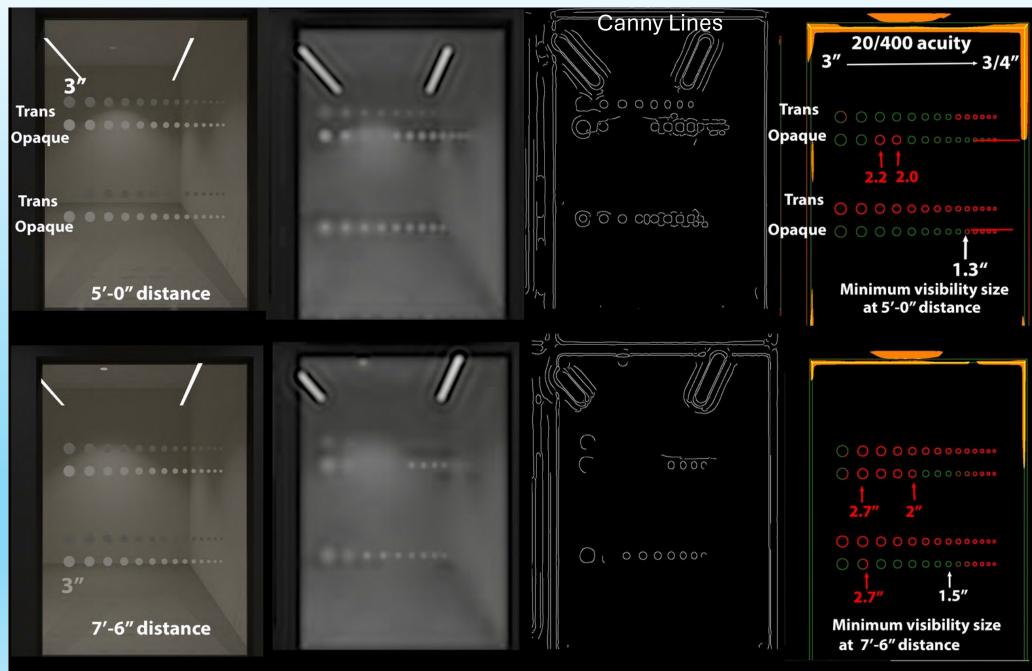
FRIT Visibility Study: Visually Impaired Residence Hall Glass Partitions

Translucent:

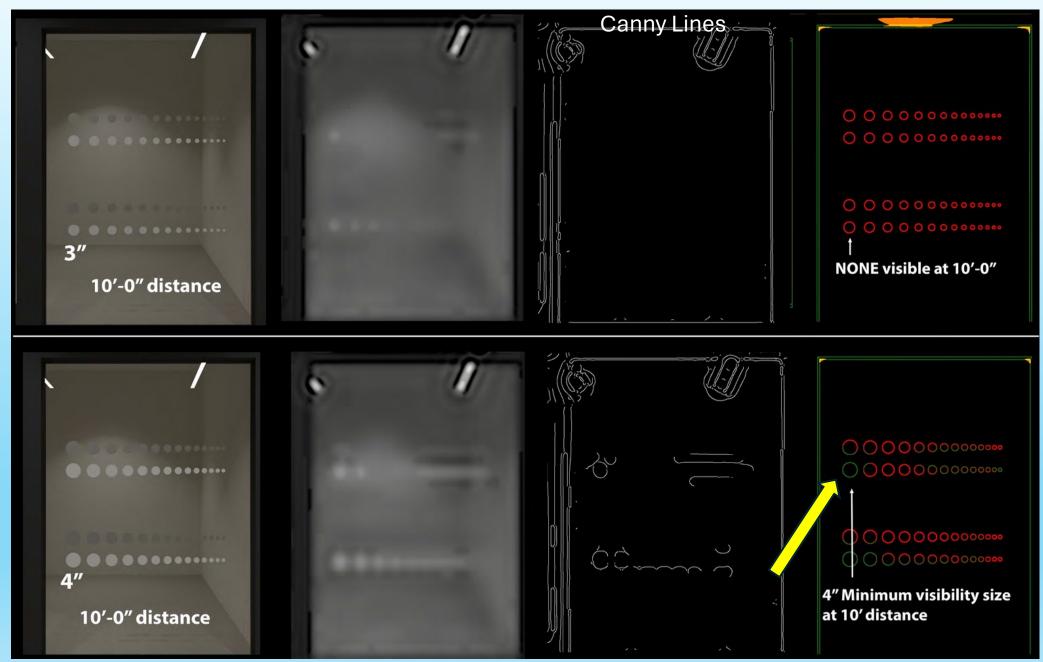
Etched



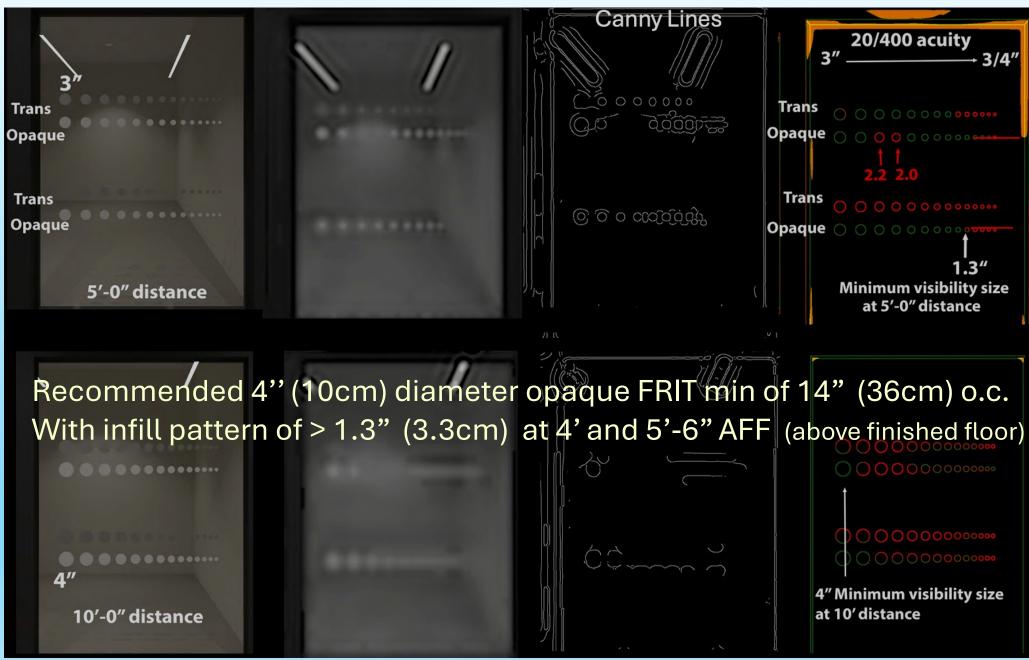
FRIT Visibility Study:



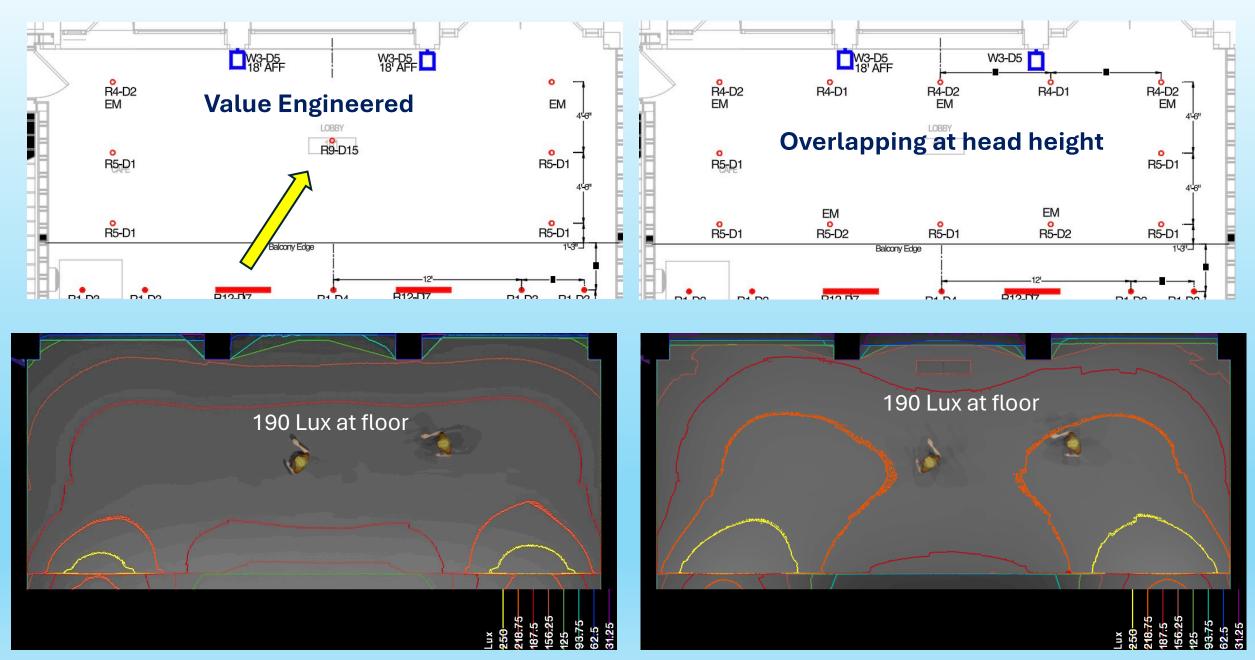
FRIT Visibility Study:



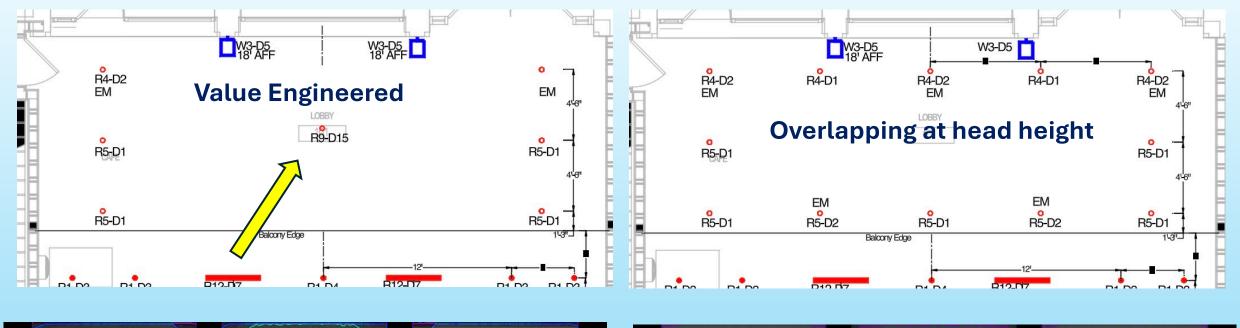
FRIT Visibility Study Recommendation

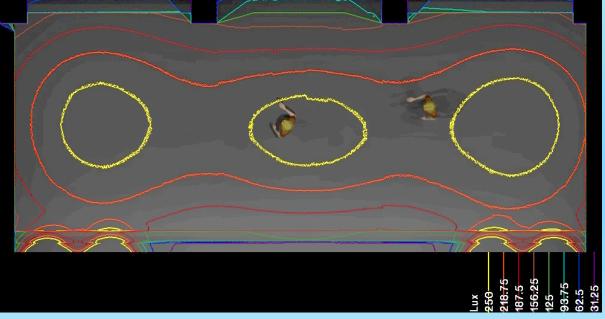


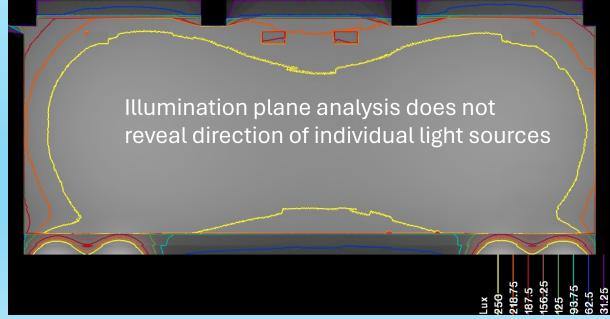
Lobby with 28' ceiling: both approaches meet the goal of +150 Lux floor

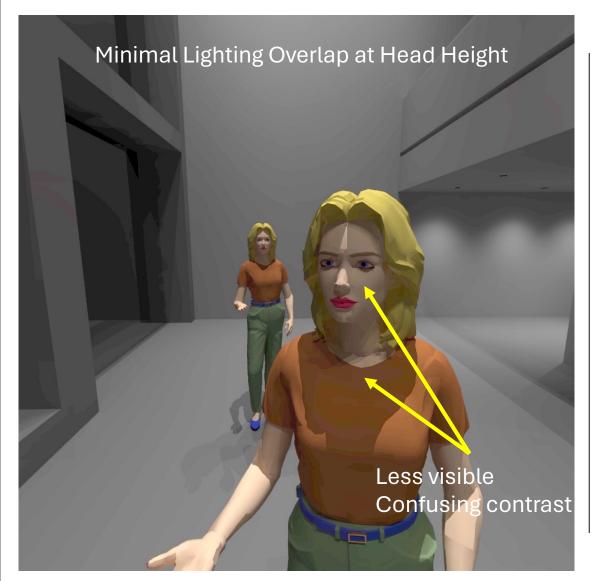


Compare Illumination at 5' AFF for LV Face Visibility and Sign Language

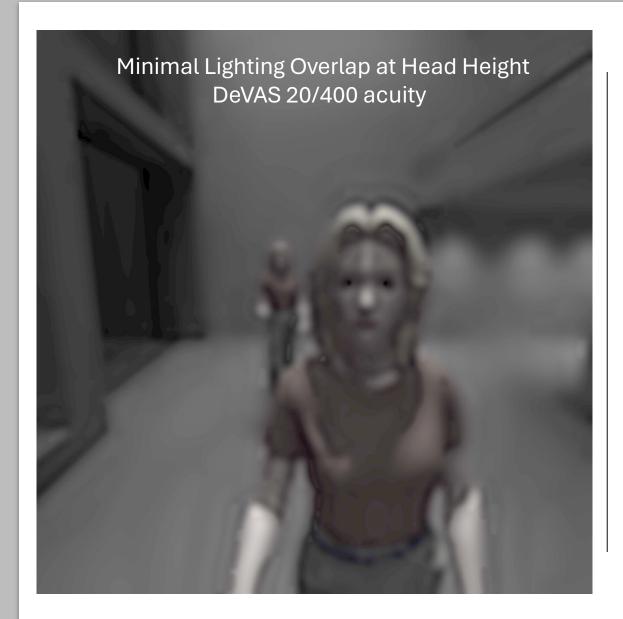


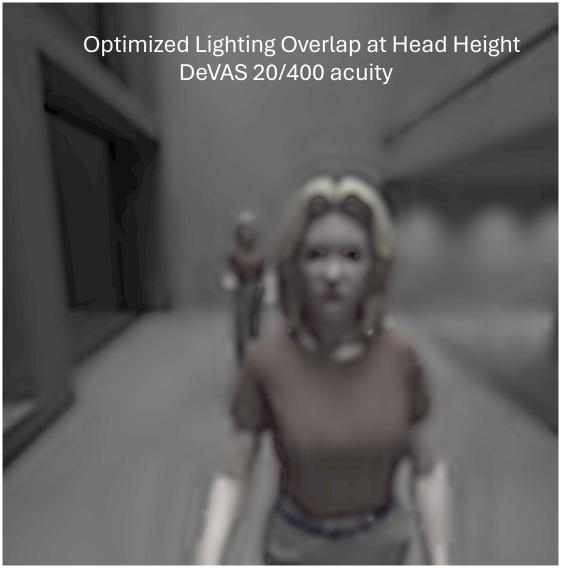












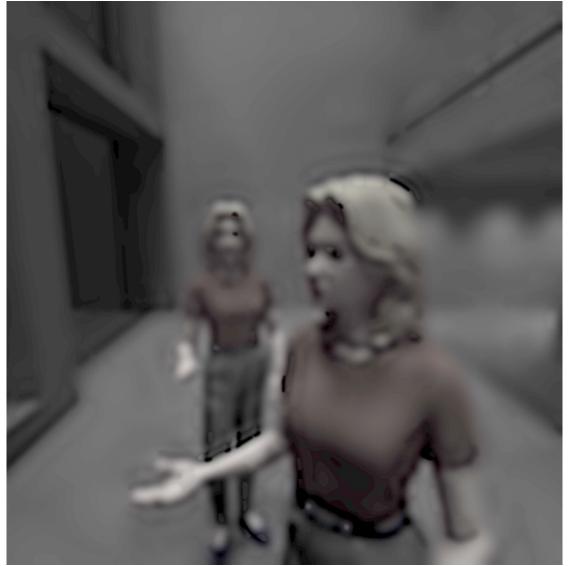


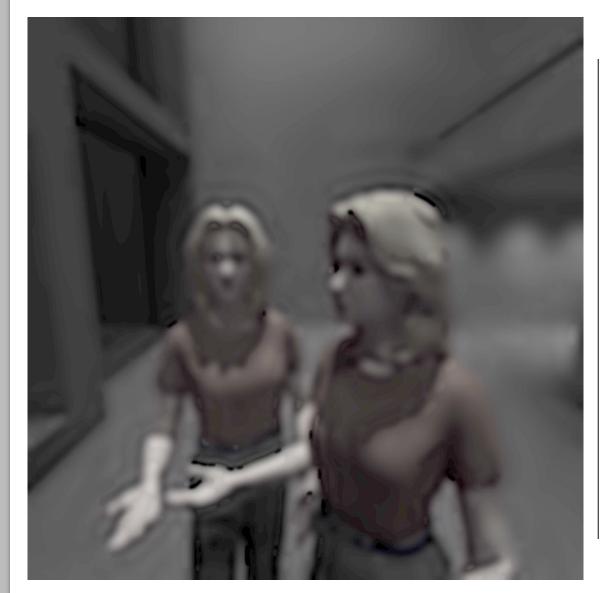


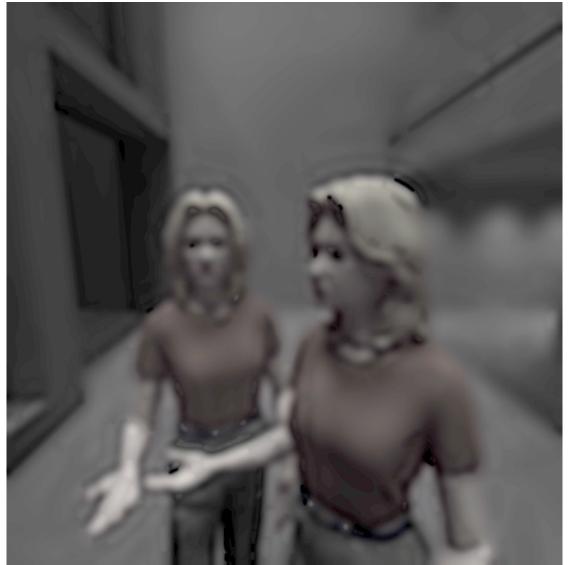




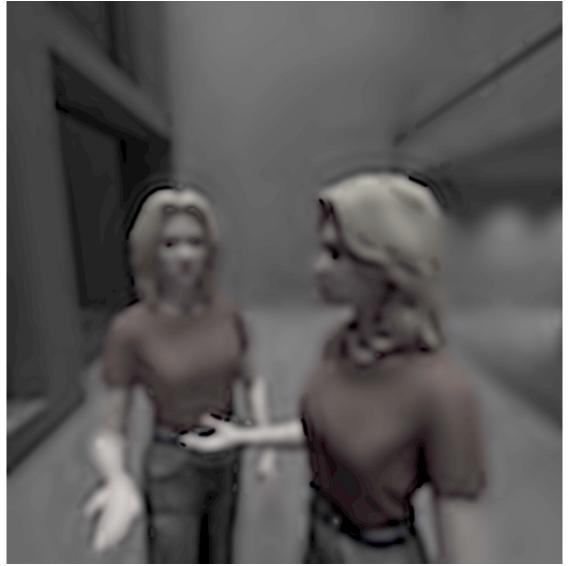












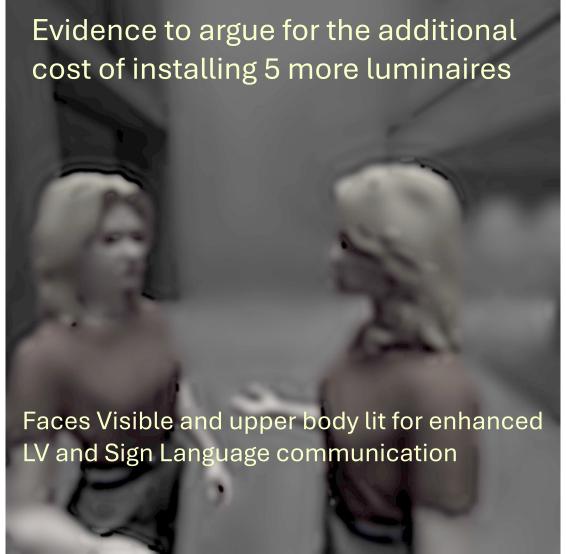




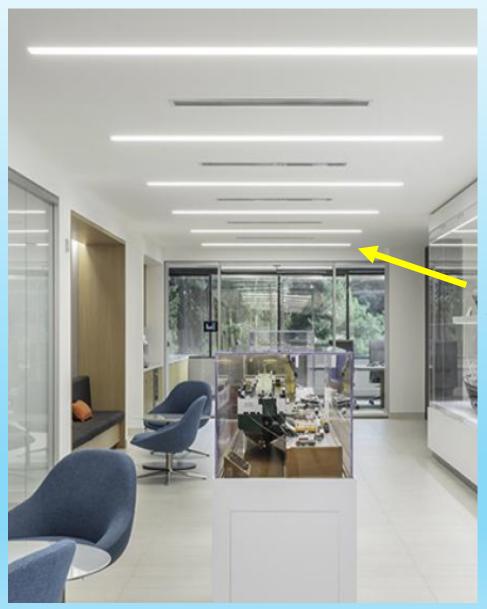




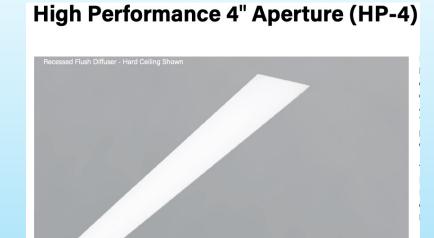


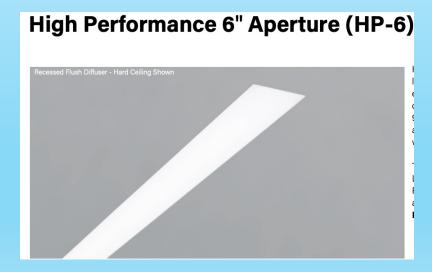


Searching for an Egress Wayfinding marker visible at ~25'

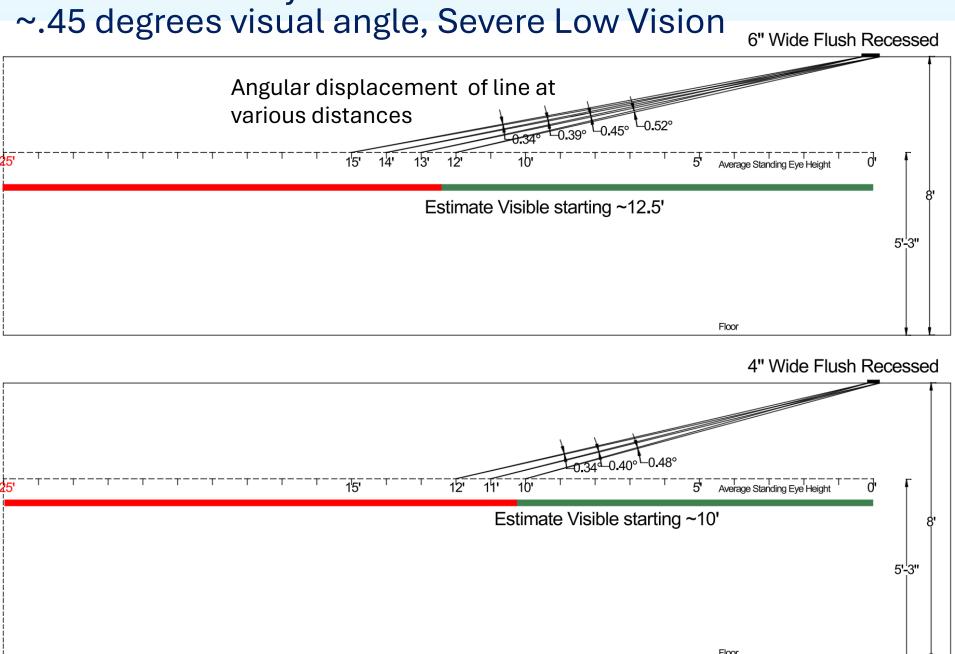


Is this line of light visible at 25' with 20/400 acuity? (If other recessed lighting is UGR 0)

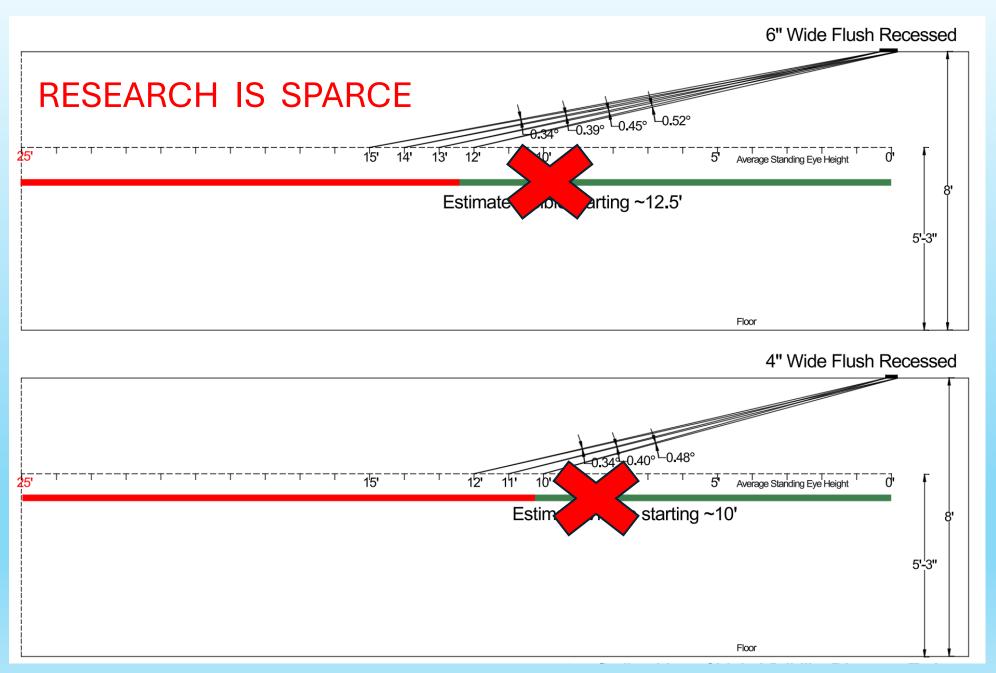




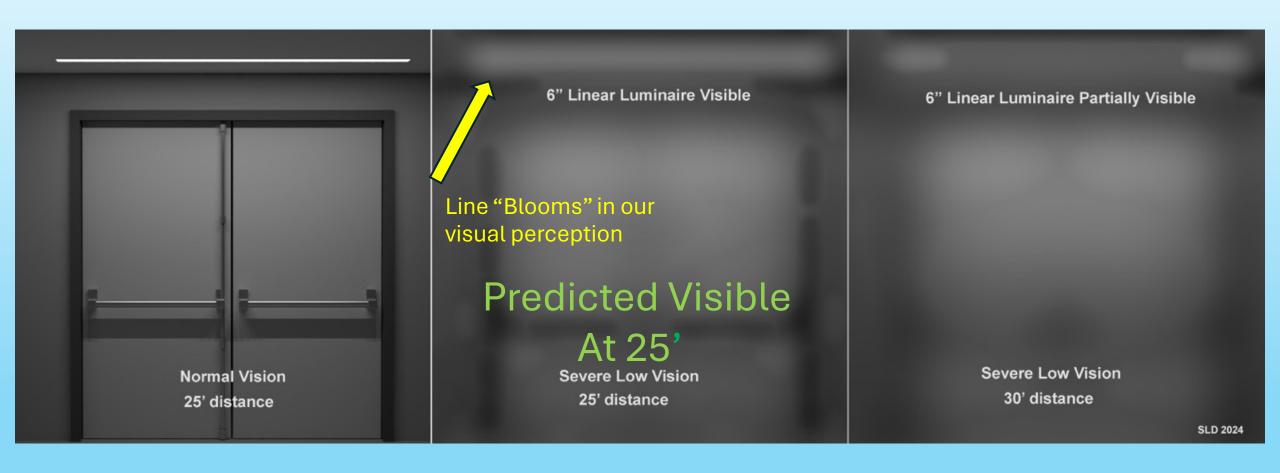
LV Non-Luminous Visibility of 4" & 6" wide linear black line in 8' ceiling



But what about the Visibility of a flush 4" & 6" luminous luminaire 8' ceiling

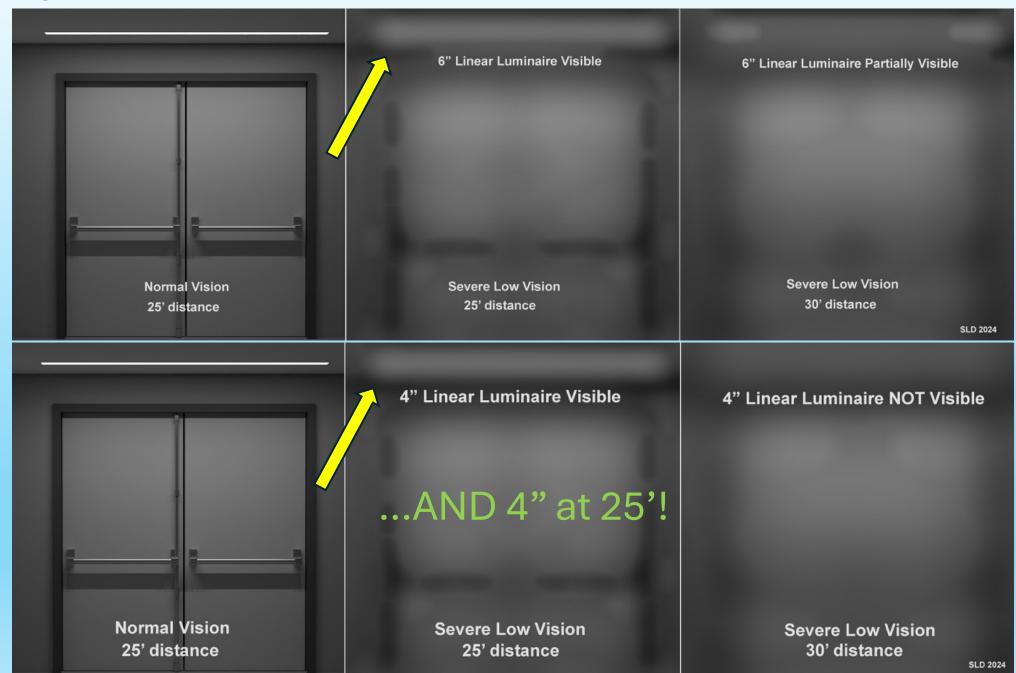


Applying DeVAS... 6" wide luminaire at 25'

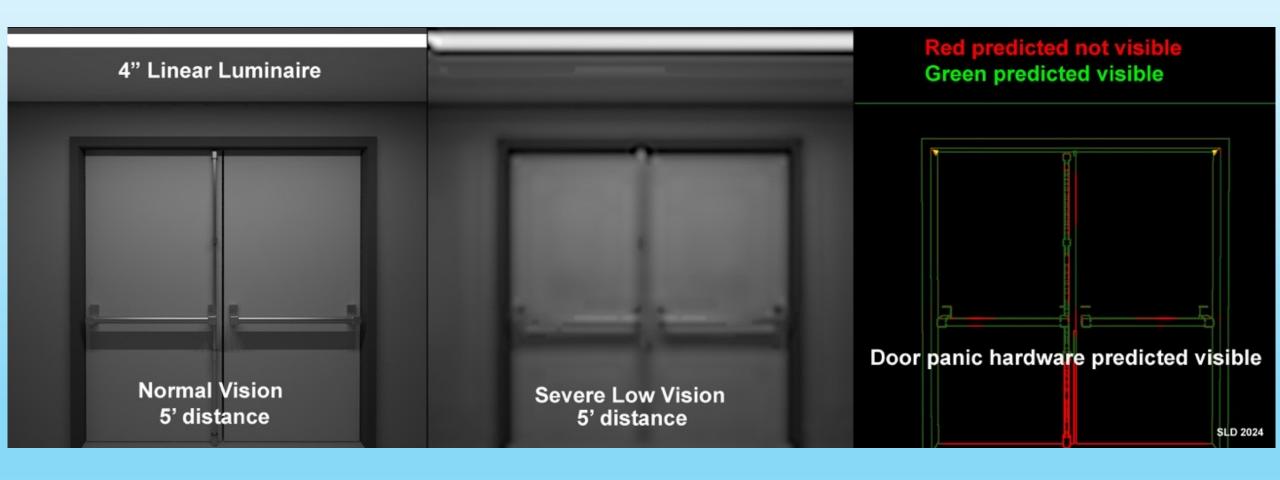


Indicates 6" luminaire predicted visible at 25'

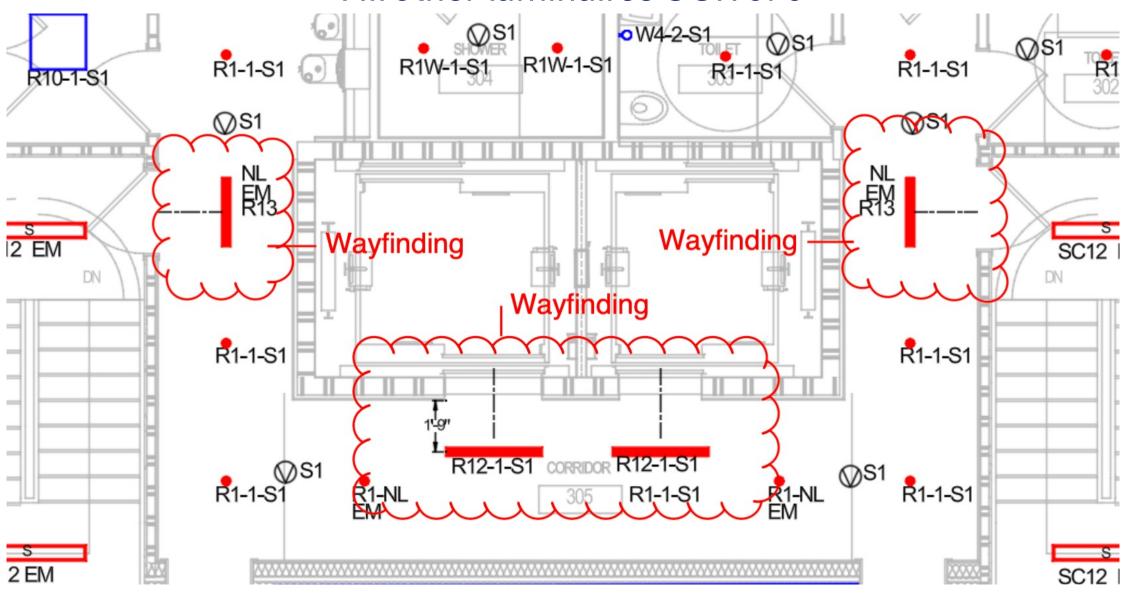
Applying DeVAS... 6" AND 4" luminaire at 25'



Door Panic Hardware predicted visible from 5' or closer



Informing the Design: Wayfinding using 4" wide flush linear at Egress Doors All other luminaires UGR of 0



Deploying **GLARE** as an advantage

NEW Low Vision Visibility Analysis Research Project

EVA R01 1st Year Progress Report

Enhancing Visual Accessibility

2025.05.01

Johns Hopkins University, Department of Ophthalmology in conjunction with Wilmer Eye Institute and Clinic

Project Goal

Develop an objective tool for evaluating the visual accessibility of indoor environments.

(for use by Field Clinicians when visiting patient residences)

Does not use Radiance, but this project extends the work of DeVAS, which is Radiance based... spawn of DeVAS!

Team Structure



Arathy Kartha (SUNY)

Project Goal – Algorithm Development

Enter Vision Status Visual Acuity: Contrast Sensitivity:



1. Low vision simulation (RGB)



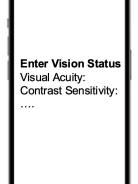
Hazard flagging

3. Edge-based analysis (RGB and depth)

2. Object-based analysis (RGB)

Project Goal – Software Development

1. Photometric fidelity (Camera)









2. Depth accuracy (LiDAR)

3. Algorithm implementation

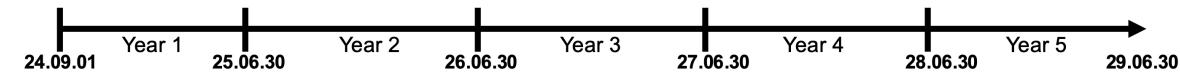
5-year Project timeline

Implementation at home and clinic

Algorithm development and validation

Aim2





Sensor testing

Algorithm implementation

Upgrading, utility study, manual

Aim1

Aim3

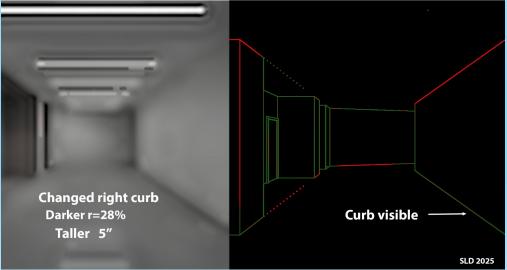






DeVAS is demonstrated effective for **Low Vision visibility analysis** and as a **visual hazard detection tool** in architectural projects













DeVAS can assist in improving the quality of life and safe passage for many Please help in promoting these tools

Developers needed!!



