Comparing real and virtual HDR-scenes

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Outline

- 1. Introduction
- 2. Goal: "There Reality"
- 3. First experiment
- 4. Future tasks

Introduction

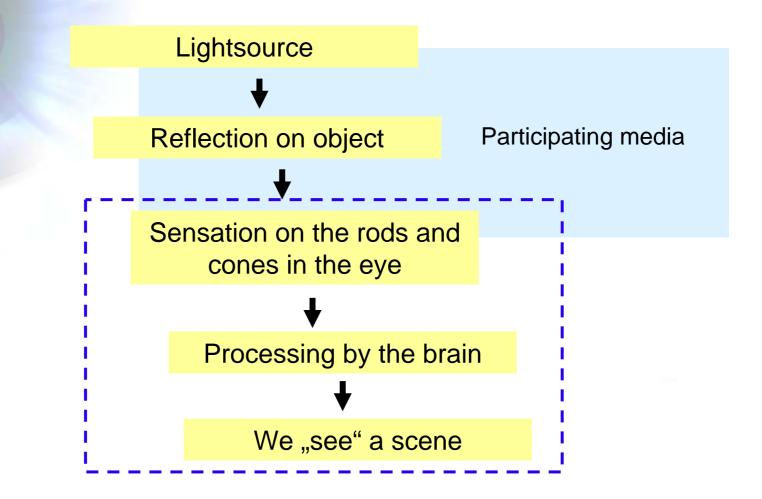
- What is reality?
- A scene seen by our eyes?
- A physically correct rendering?
- A photograph?
- A painting?

. . .

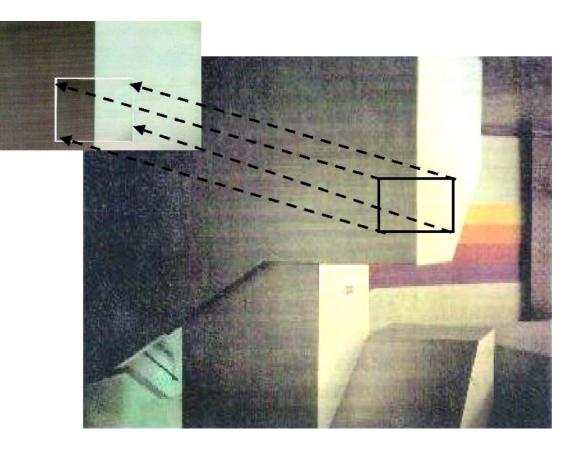




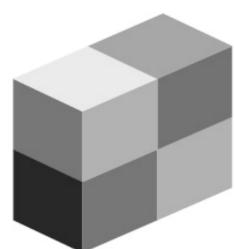


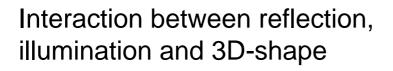


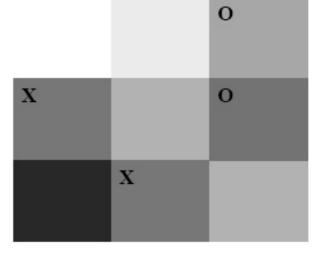












How to parameterize "reality"

Simulate a scene as physically correct as possible

> physically correct should be real?

Most attempts are not real enough. E.g. photorealism (only LDR).

Or computational too expensive

Bristol

Graphics

Computer

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"There Reality"

"As real as if you are there"

"There Reality"

 No need to be 100% physically correct

(only as correct as it has to be so that humans think they are there)

Benefits:

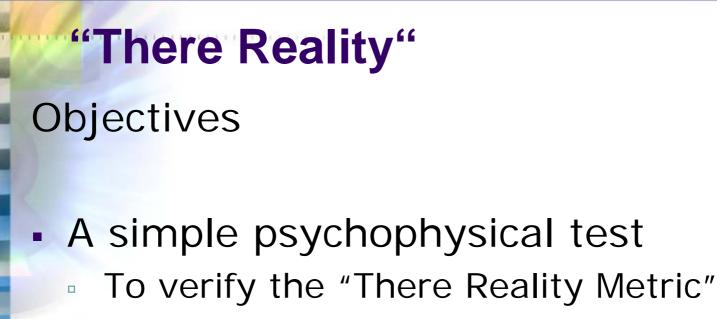
- Saves computation cost
- "Reality in Real Time" is possible in the near future

Image metrics

 Implement the parameters into a Gold Standard

Create an image metric

Some Present Image Metrics:VDPPdiff



- a new version of an image metric like VDP
 - To test if renderer is producing "reality"
 - To compare renderers with each other

Scientific fields

- HVS

- Phsychophysics
- Evolutionary Biology
- Vision affected by culture
- Present image metrics
- Renderer



Hypotheses

 The scenes displayed on the Brightside HDR-Display are more "real" than scenes presented on a normal LDR-display.

 It allows the presentation of "thererealistic" images

Experiment 1

 Test if the human judgement of lightness doesn't see a difference between real and HDR-monitor scene

Previous Work

 Ann McNamarra (2000): Comparing Real and Synthetic Scenes using Human Judgment of Lightness

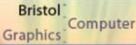
 Alan Gilchrist et al. (1999)
 Anchoring Theory of Lightness Perception



Scenes to compare

HDR

- real scene with real objects
- HDR photograph on HDR-monitor
- HDR rendering of scene (rendered with Radiance-Software)
- HDR rendering of scene (other renderer such as CameoSim, ...)



Scenes to compare

LDR

LDR photograph of scene (some elements are either over- or underexposed)

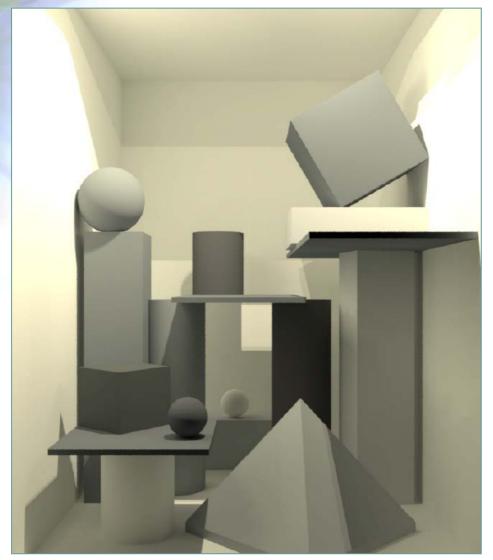
 tonemapped HDR photograph to fit on LDR-display (different tonemappers)

Methods

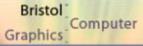
- The method follows the one of McNamara (2000)
- Changes:
 - Is extended to HDR.
 - Use of glossy or semiglossy objects
- Test will be carried out in October at Bristol University



Scene



Source: McNamara, 2000



Paints



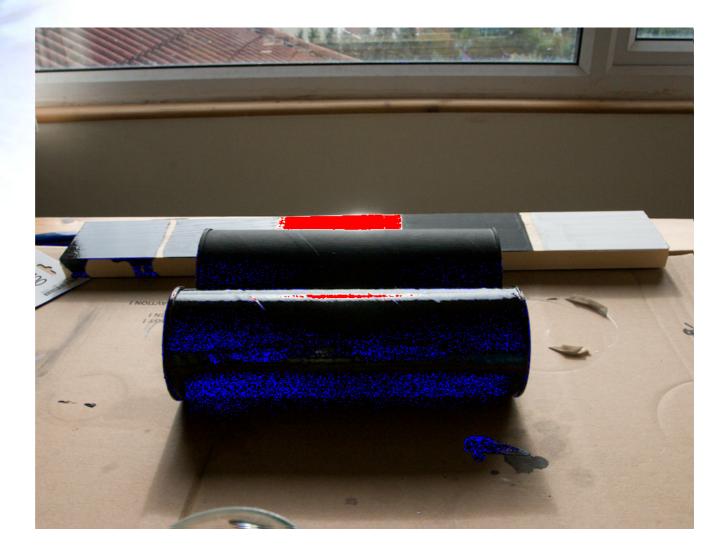
 Glossy, 0%
 Glossy, 50%
 Glossy, 100%
 Matte, 0%
 Matte, 100%

 8Bit-val
 13
 34
 232
 43
 226







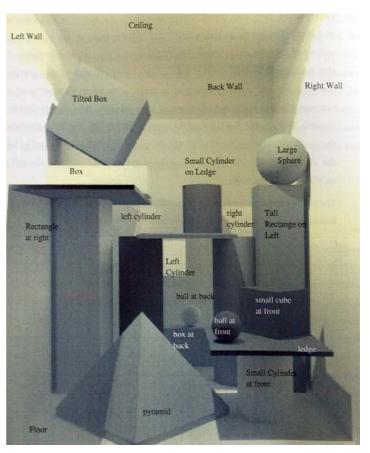


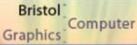
Real Scene

Box containing basic geometric objects

Lightsources and reflectance of objects/materials are calibrated.

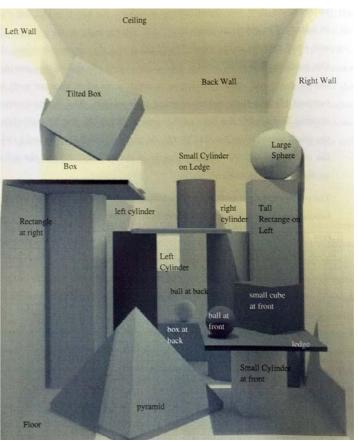
Source: McNamara, 2000





Synthetic Scene

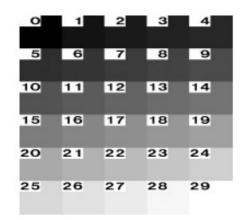
- Same like real scene
- Created using Radiance



Task for participants

Match the reflectance of all object in the scene to a Munsell chart





Task for participants

- The HVS has limitations so there will be systematic errors
- Both sets of lightness errors should be close to each other if the rendered image is perceived as "real"

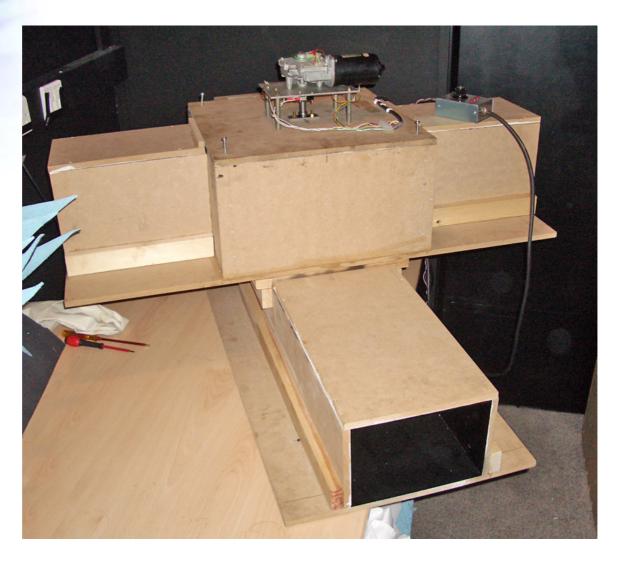
Estimate the contrast of the object seen to a reference

Periscope

- Allows to switch between three different Scenes.
- Real scene

- HDR-Monitor
 - LDR-Monitor
- This switch is not visible to the participant.

Periscope



Problems

 Has the HDR-Display enough dynamic range to display a "real" scene without tonemapping?

 Does the use of a "periscope" reduce the "realness" of a scene? (only a "window" to reality)?

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Further research

Future tasks

More complex objects and elements in the scene

use monochromatic colour

use of full colour

 increase the complexity of the geometry

Future tasks

- Implemetation into software
- what is more important:
 - Colour
 - Glossiness
 - Shape
 - Etc...



Summary

- Figure out what makes a scenes believable real – "There Reality"
- Create a Gold Standard
- Create a simple psychophysical test to verify the Gold Standard
- Implement that into an image metric

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